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A LIF-based Legendre Memory Unit as neuromorphic State Space Model benchmarked on a second-long spatio-temporal task

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The LMU architecture

Legendre Memory Unit - I

The LMU foundation is in the shifted Legendre polynomials

$$P_i(x) = (-1)^i \sum_{j=0}^i \binom{i}{j} \binom{i+j}{i} (-x)^j$$

which are used as basis to project a signal $u(t)$ with temporal delay $u(t - \theta')$ within a sliding window of duration θ with $0 \leq \theta' \leq \theta$:

$$u(t - \theta') \approx \sum_{i=0}^{d-1} P_i\left(\frac{\theta'}{\theta}\right) m_i(t)$$

The highest order $(d - 1)$ in the series expansion is related to the dimension d of the memory state-vector $\mathbf{m}(t)$ defined as

$$\theta \dot{\mathbf{m}}(t) = \mathbf{A}\mathbf{m}(t) + \mathbf{B}u(t)$$

with \mathbf{A} and \mathbf{B} representing the ideal state-space matrices determined using the Padé approximants:

$$\mathbf{A} = [a]_{ij} \in \mathbf{R}^{d \times d}; \quad a_{ij} = (2i + 1) \begin{cases} -1, & i < j \\ (-1)^{i-j+1}, & i \geq j \end{cases}; \quad \mathbf{B} = [b]_i \in \mathbf{R}^d; \quad b_i = (2i + 1)(-1)^i; \quad i, j \in [0, d - 1]$$

Legendre Memory Units: Continuous-Time Representation in Recurrent Neural Networks

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Voelker et al, *Advances in Neural Information Processing Systems 32 (NeurIPS 2019)*

Legendre Memory Unit - II

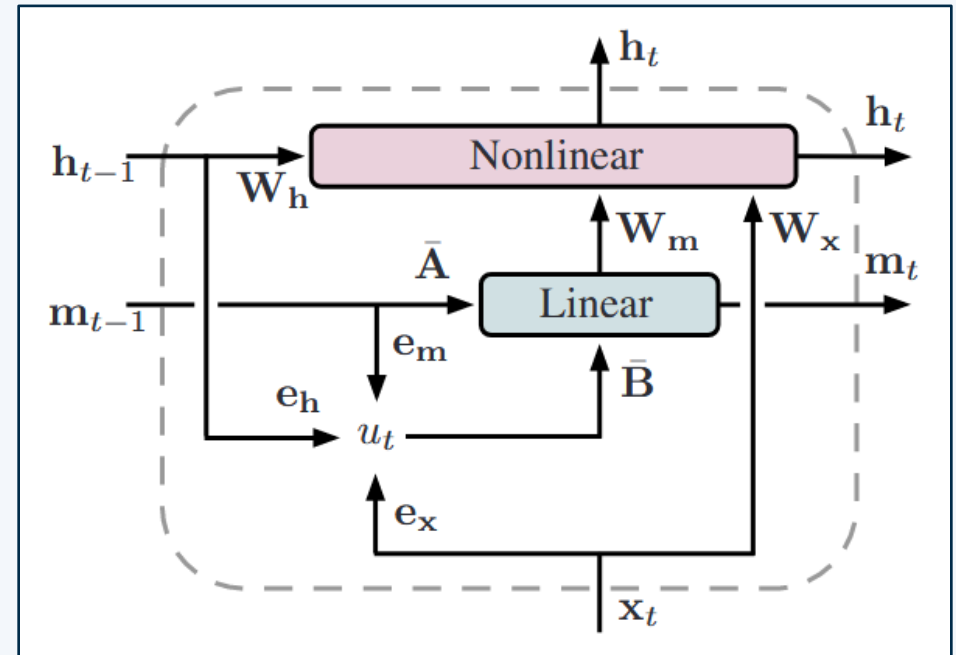
The LMU takes an input \mathbf{x} and produces a hidden state \mathbf{h} and a memory state \mathbf{m} to define the new representation u through learnable encoding vectors \mathbf{e} and learnable kernels \mathbf{W} .

Discretization and layer definitions:

$$\mathbf{m}_t = \bar{\mathbf{A}}\mathbf{m}_{t-1} + \bar{\mathbf{B}}u_t; \quad \bar{\mathbf{A}} = (\Delta t/\theta)\mathbf{A} + \mathbf{I}, \quad \bar{\mathbf{B}} = (\Delta t/\theta)\mathbf{B}$$

$$\mathbf{h}_t = f(\mathbf{W}_x\mathbf{x}_t + \mathbf{W}_h\mathbf{h}_{t-1} + \mathbf{W}_m\mathbf{m}_t)$$

$$u_t = \mathbf{e}_x^T\mathbf{x}_t + \mathbf{e}_h^T\mathbf{h}_{t-1} + \mathbf{e}_m^T\mathbf{m}_{t-1}$$



Voelker et al, *Advances in Neural Information Processing Systems 32 (NeurIPS 2019)*

Our LIF-based LMU (L²MU)

Leaky Integrate-and-Fire (LIF) neurons inside LMU

We redesigned the LMU architecture to **fully rely on LIF neurons**^{[1],[2]}:

$$RC \frac{dU(t)}{dt} = -U(t) + I(t)R$$

where $U(t)$ is the **membrane potential** and $I(t)$ is the **input current**, while R and C refer to the electrical equivalent and they define the decay constant τ_{mem} of the *leaky integrator*.

For our **L²MU**, we used the `Leaky` neuron model available in `snnTorch`^[3]:

$$U_t = \underbrace{\beta}_{\text{membrane potential decay factor}} U_{t-1} + \underbrace{W X_t}_{\text{input}} - \underbrace{S_{t-1} \Theta}_{\text{reset by subtraction}}$$

Spiking condition:

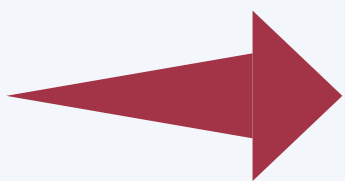
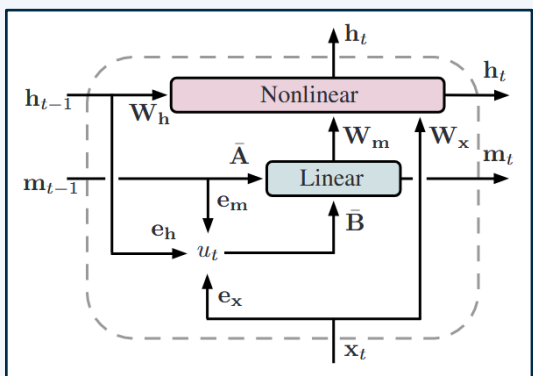
$$S_t = \begin{cases} 1, & \text{if } U_t > \Theta \\ 0, & \text{otherwise} \end{cases}$$

1. Gerstner and Kistler. Cambridge University Press, 2002
2. Eshraghian et al, Proceedings of the IEEE, 2023
3. github.com/jeshraghian/snntorch/tree/master

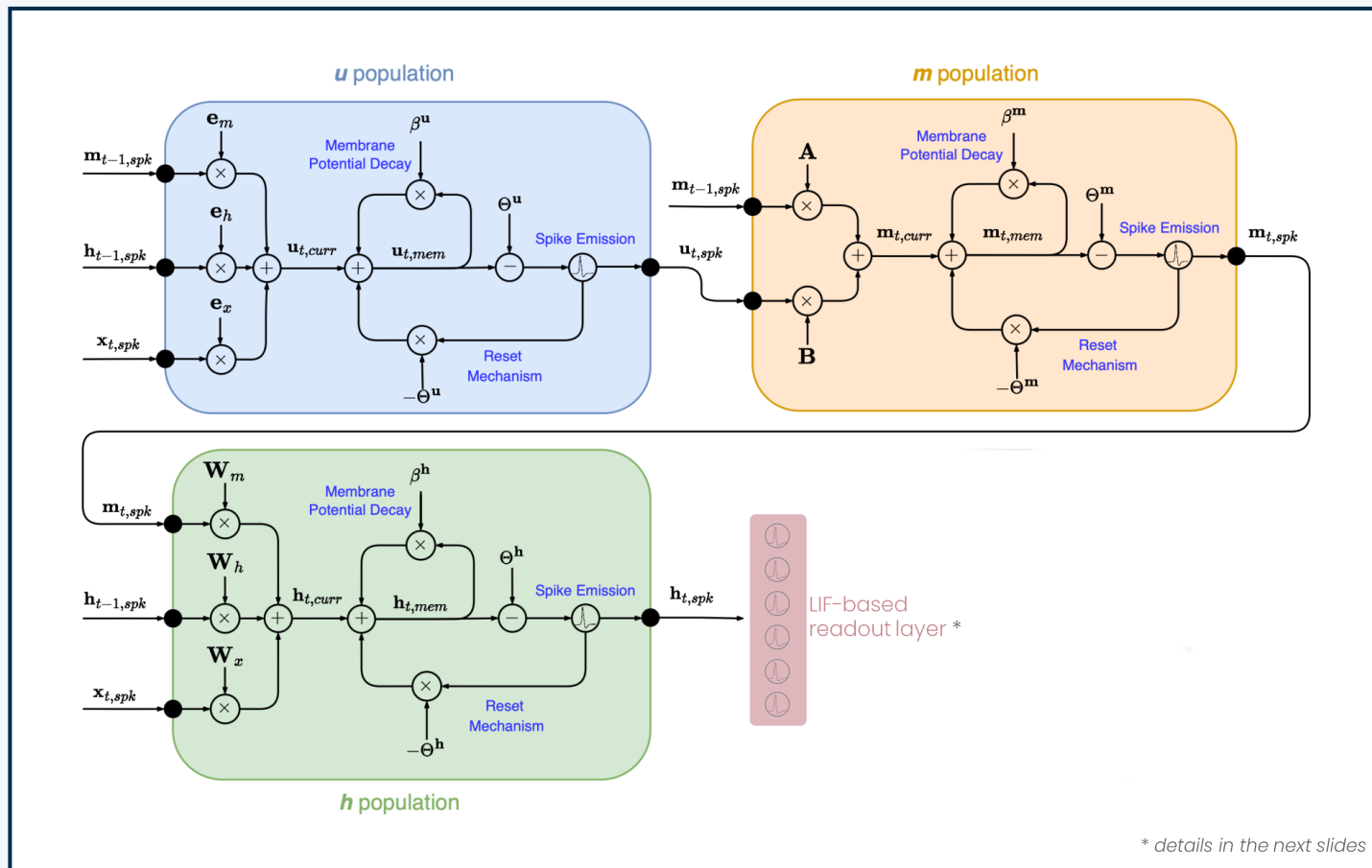
Our LIF-based LMU (L^2MU)

The L^2MU architecture

Each of the original LMU blocks is converted into a dedicated **population of LIF neurons**:



Voelker et al, *Advances in Neural Information Processing Systems 32 (NeurIPS 2019)*

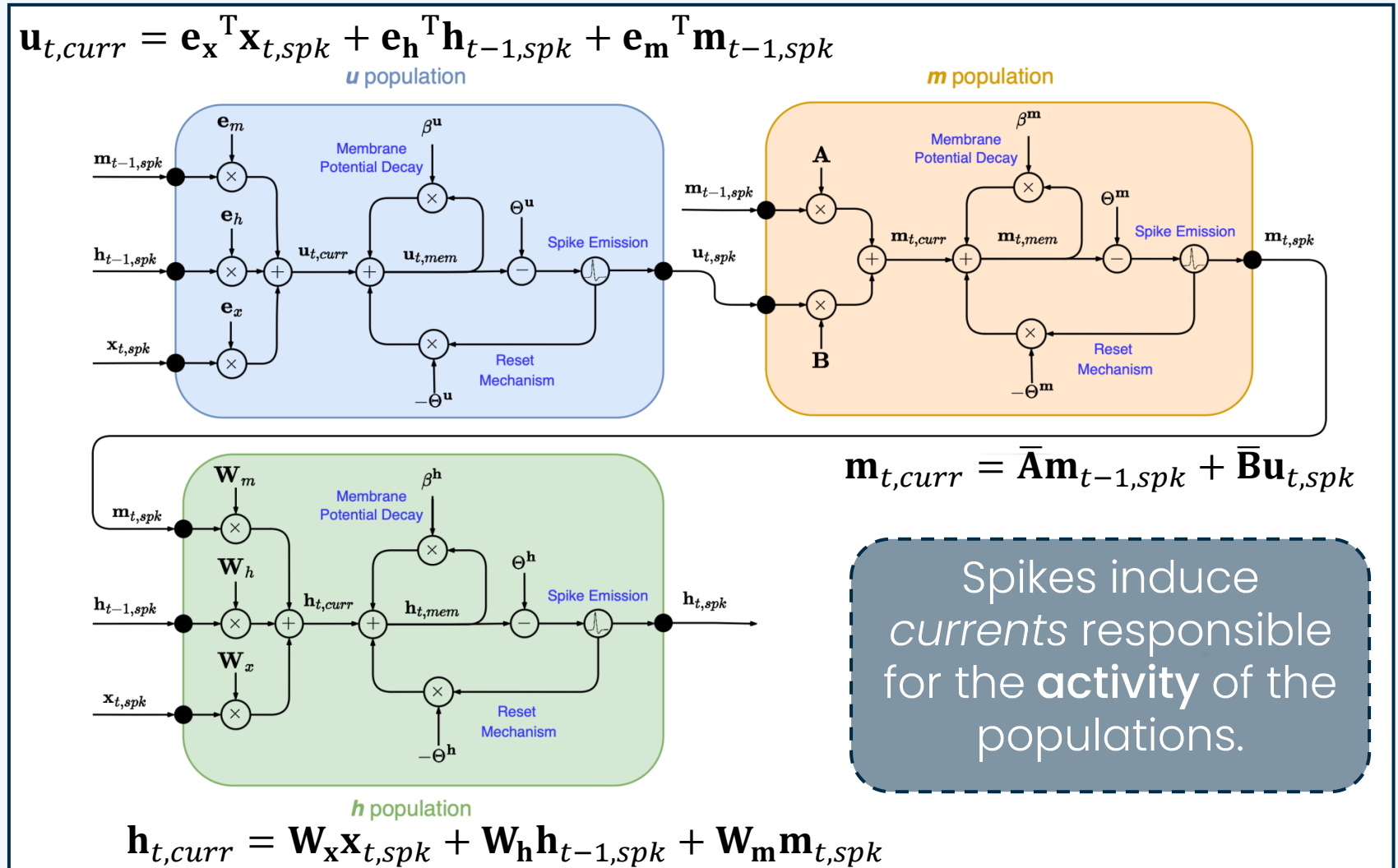


* details in the next slides

The L^2MU equations

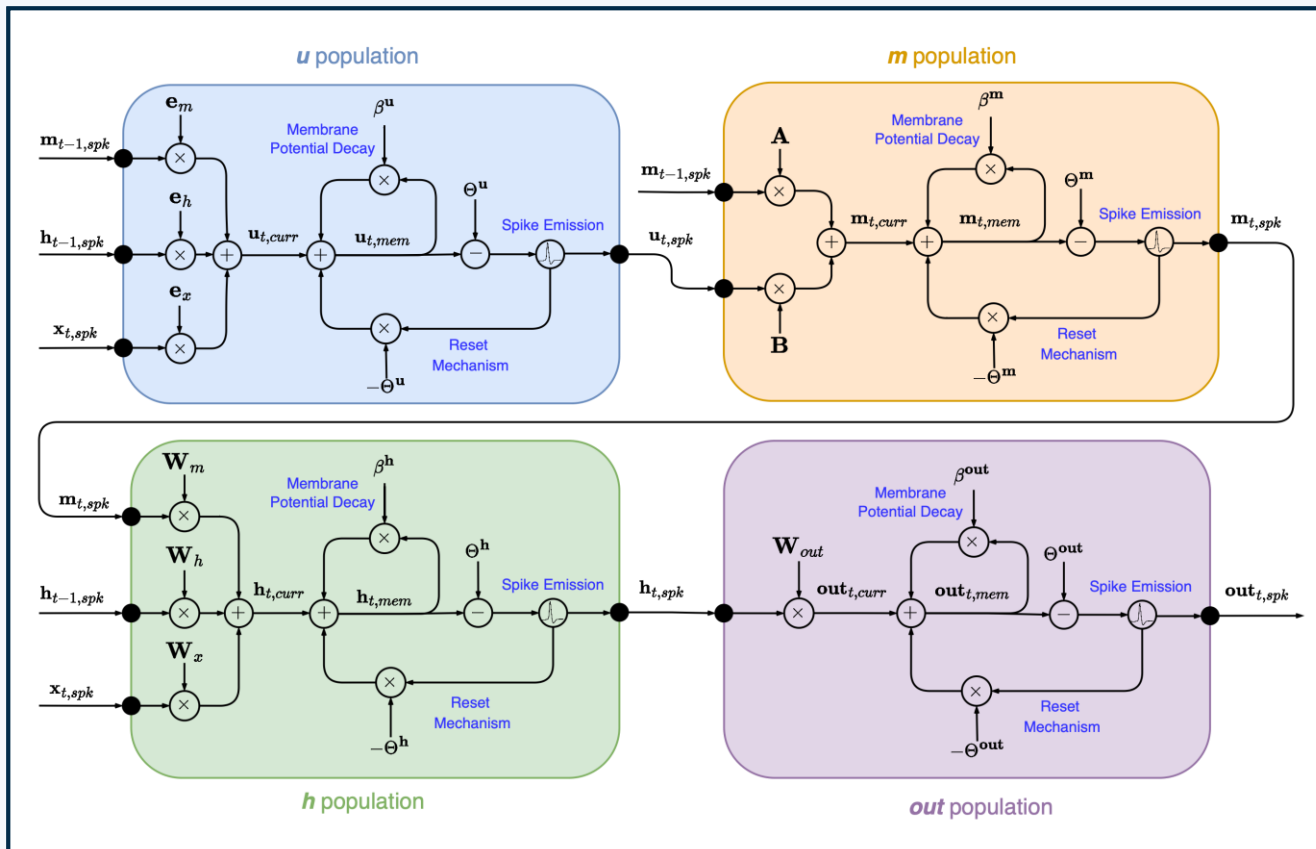
We rewrote the original LMU equations in such a way that each block, i.e. population:

- a. transmits **spikes**
- b. receives **spikes**



The complete model

The readout layer is made of an additional population of LIF neurons, the *out population*, which receives spikes from the *h population*:



The **spiking activity** of the *out population* is used to make predictions

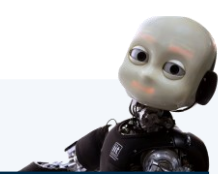
Every layer and all the populations underwent **hyperparameter optimization** through the Neural Network Intelligence toolkit^[1].

1. github.com/microsoft/nni

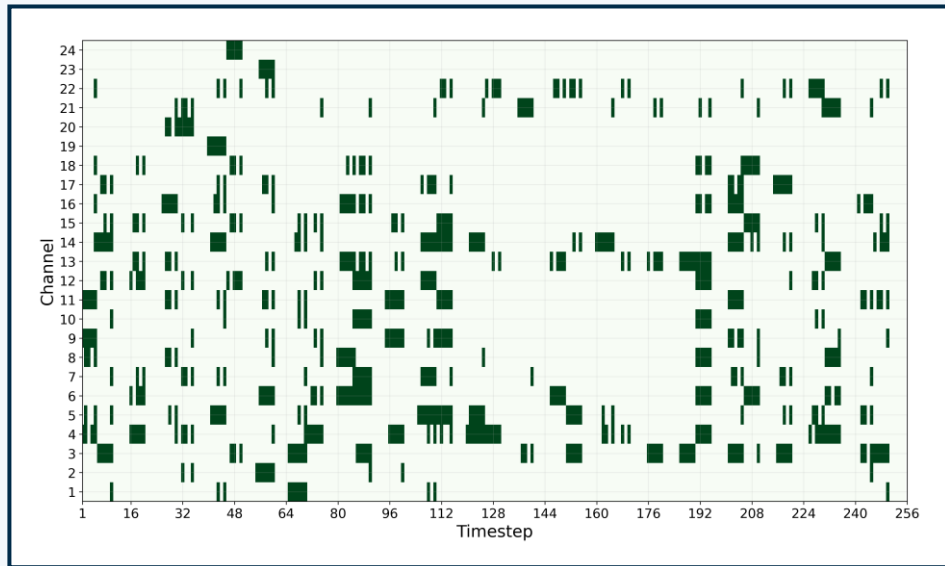
Braille letter reading

Second-long spatio-temporal task

The Braille dataset^[1] contains pressure readings from the iCub artificial fingertip sliding over individual Braille characters and collecting samples of 1.35 s.

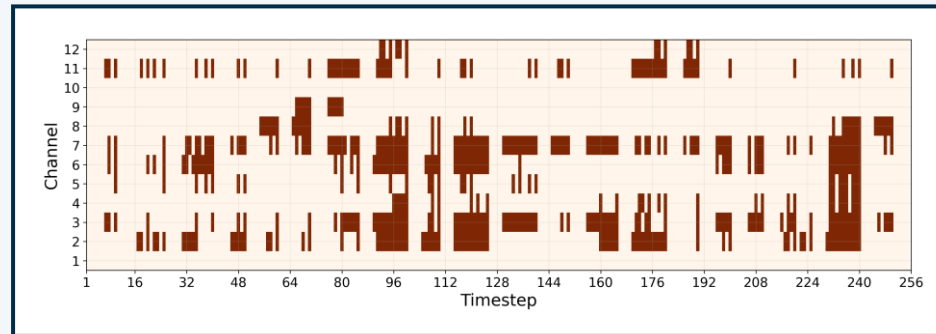


Complete dataset:
26 characters and 'space'



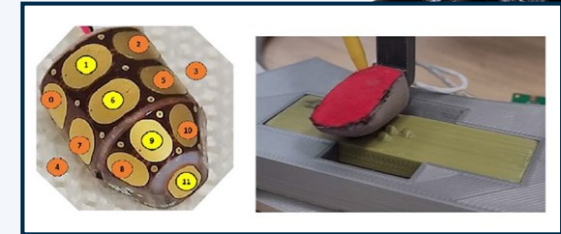
Müller-Cleve et al, *Frontiers in Neuroscience* 16:951164, 2022

7-class subset:
{'A', 'E', 'I', 'O', 'U', 'Y', 'Space'}



$$Ch_{i,subset} = Ch_{2i,whole} \vee Ch_{2i-1,whole}$$

Events are created from the pressure readings through sigma-delta modulators.



Müller-Cleve et al, *Frontiers in Neuroscience* 16:951164, 2022

Pedersen et al, *Nature Communications* 15:8122, 2024

1. [10.5281/zenodo.7050094](https://doi.org/10.5281/zenodo.7050094)

Classification accuracy and NeuroBench^[1] results

Müller-Cleve et al., Frontiers in Neuroscience 16:951164, 2022

Pedersen et al., Nature Communications 15:8122, 2024

Braille dataset	Signal type	Architecture	Accuracy (%)
Complete	Encoded*	Spiking RNN	81.8
		LSTM	82.3
Complete	Encoded	L ² MU	85.6
7-class subset	Encoded	Spiking RNN	95.0
7-class subset	Encoded	L ² MU	97.1

Complete dataset

Metrics	Value
Test accuracy	85.55%
Parameters	4.90×10^5
Footprint	1.96 MB
Connection sparsity	0.13
Activation sparsity	0.97
Membrane updates	2.39×10^5
Effective MACs	0
Effective ACs	2.04×10^6
Dense operations	12.67×10^7

7-class subset

Metrics	Value
Test accuracy	97.14%
Parameters	1.19×10^5
Footprint	0.48 MB
Connection sparsity	0.21
Activation sparsity	0.96
Membrane updates	1.23×10^5
Effective MACs	0
Effective ACs	0.90×10^6
Dense operations	3.15×10^7

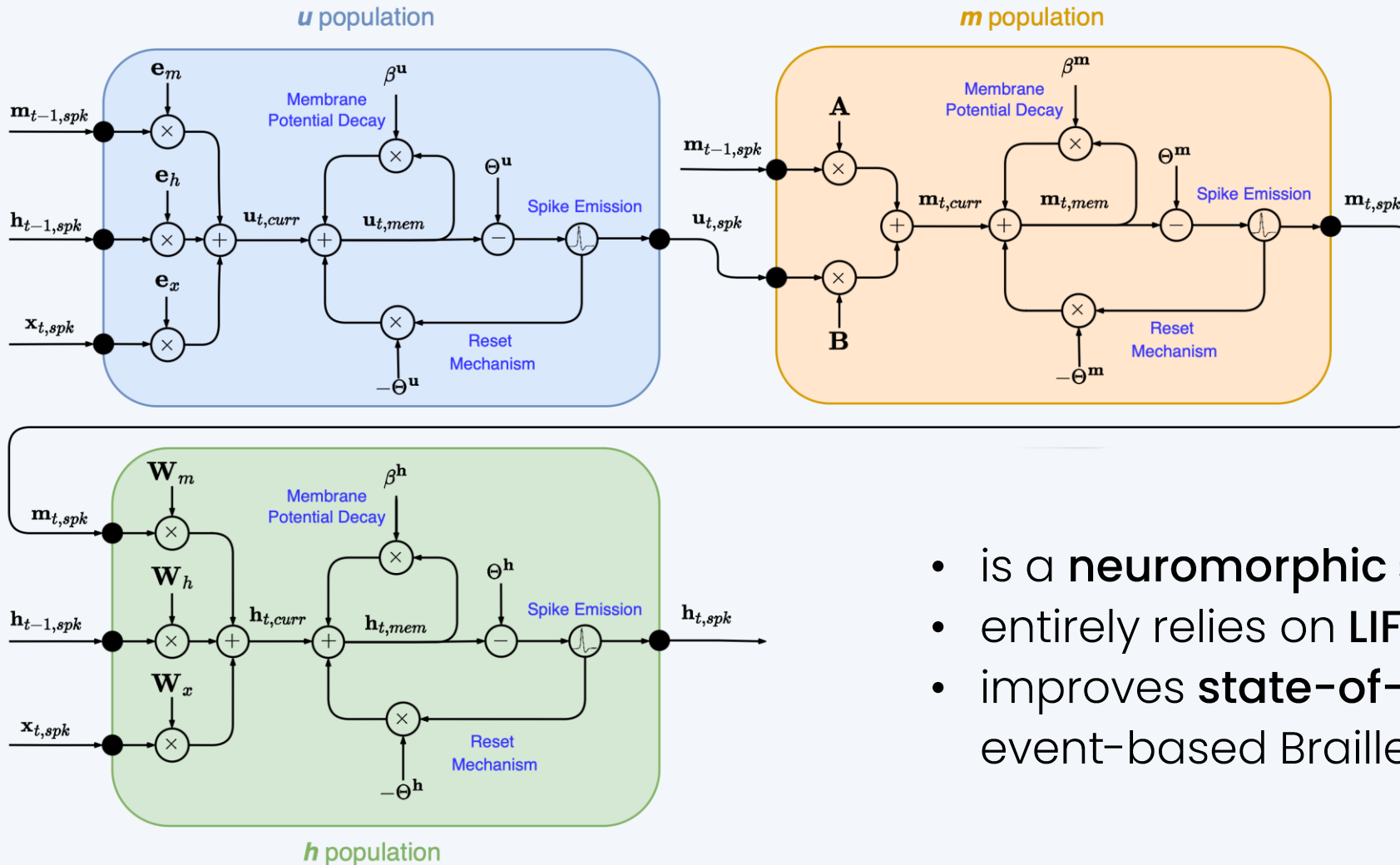
- Activation sparsity: relative number of inactive neurons within the network
- Membrane updates: number of updates of the neurons' membrane potential
- Effective MACs: number of operations with non-binary activations
- Effective ACs: number of operations with binary activations

1. Yik et al., Nature Communications 16:1545, 2025

Conclusion



Our **LIF-based LMU (L²MU)**:



- is a **neuromorphic state space model**
- entirely relies on **LIF neuron populations**
- improves **state-of-the-art** results on event-based Braille letter reading

Thank you!



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