NEUROMORPHIC AND AIRESEARCH AT BCAI

THOMAS PFEIL MARCH $16^{TH} 2021$ NICE 2021

Neuromorphic and AI research at BCAI Outline

- Introduction to Bosch and BCAI
- Introduction to ULPEC
- Streaming rollouts
- Spiking neural networks for spatio-temporal data streams
- Iterative neural networks
- Highlights of deep learning research



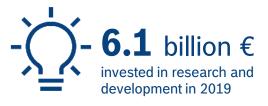
Introducing Bosch A worldwide leading IoT Company







subsidiaries and regional companies in appr. 60

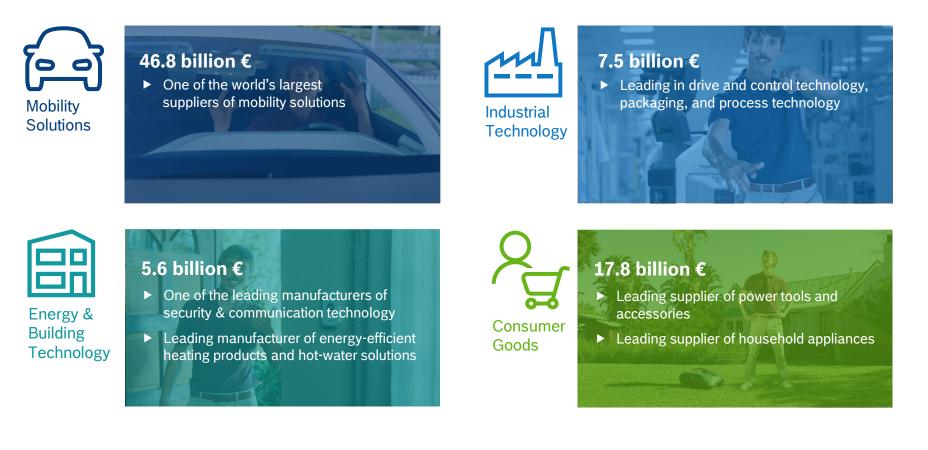








Introducing Bosch Four Business Sectors with increasing synergies





Bosch Center for Artificial Intelligence (established 2017)

Business impact and achievements

Al technology

270 AI experts* at 7 locations П. Renningen Tübingen Pittsburgh Haifa Shanghai Sunnyvale 185+ projects EUR 13m internal **264** invention reports across all functions revenue in 2019 Bengaluru **109** tier-1 publications and divisions EUR 80m savings Established Bosch as through AI in 2019 relevant AI player * status June 2020 AI learning plattform Introducing the BCAI pillars **AI Consulting AI Enabling AI Marketing AI Research AI Services** Support project strategies Build up AI competence Promote Bosch Al Gain best in class Drive commercialization

internally and externally

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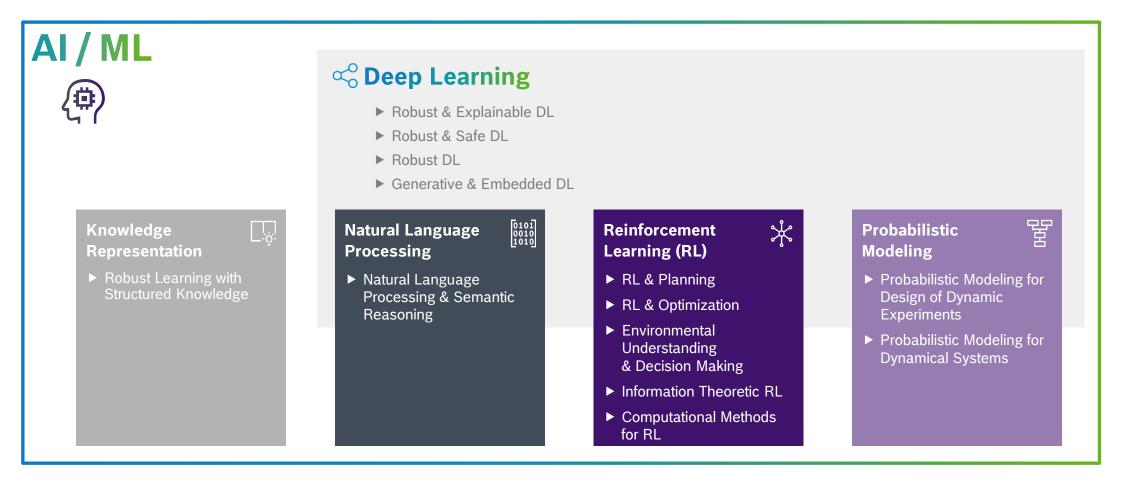
in Business units



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BCAI focus on differentiating AI research

with 13 research fields to develop safe, robust and explainable AI methods



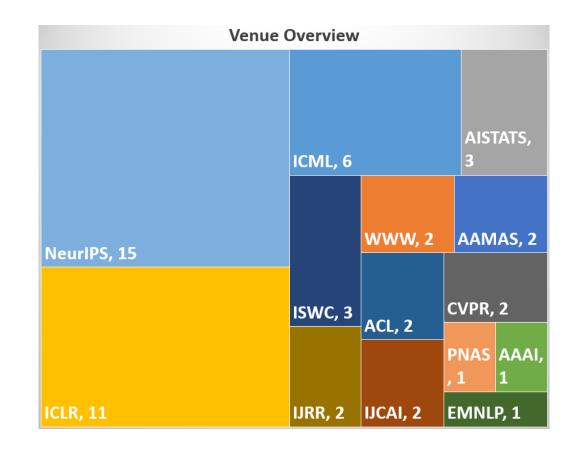
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BCAI Research 2020 Key Statistics - Publications

- ▶ 151 Researchers worldwide
- ► 38 PhD Students
- ► 53 Tier-1 Publications in 2020
- ► NeurIPS, ICML, ICLR are main venues
- ► Since 2017 #1 European company in AI research
- ► In top 11 companies @NeurIPS ins past 3 years
- ~ 200 AI-related patent applications in 2020
 - ▶ Nr. 2 in European Patent Office ranking 2019





Bosch increases activities in AI



By **2025**, the aim is for all Bosch products to either contain AI or have been developed or manufactured with its help.

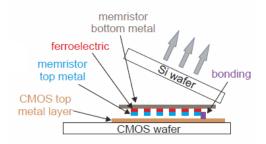
Bosch vision towards AI

Chairman of the Board of Management, Robert Bosch GmbH



Main goal

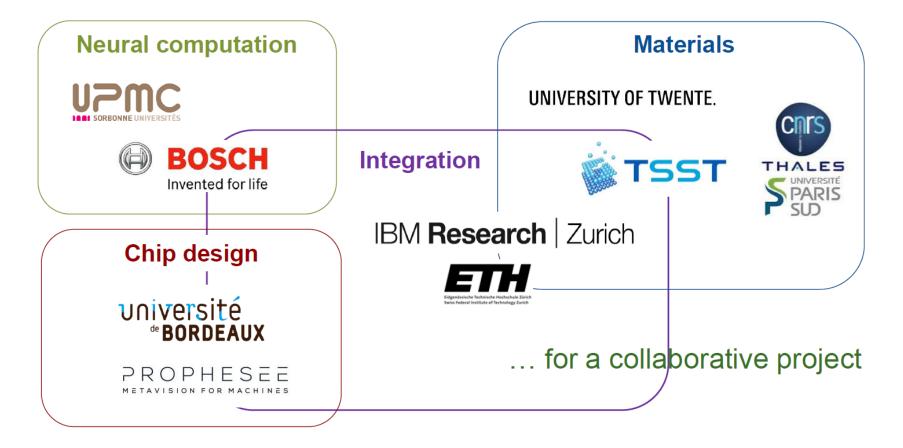
Build a smart microsystem that will exploit the benefits of event-based camera, spiking neural network and memristive technology.



Intermediate goals

- Novel device technology to establish ferroelectric memristor technology on Si
- Advanced circuit design to implement a hardware neural network based on ferroelectric memristors
- Innovative integration technology to embed on SoC the optical sensor and the memristive neural network to achieve a compact and ultra-low power system.
- Smart algorithms to natively process the output of the event-based camera by a neural network







Neuromorphic and AI research at BCAI Deep Learning With Spiking Neurons: Opportunities and Challenges



TOTAL 49,412

REVIEW ARTICLE Front. Neurosci., 25 October 2018 | https://doi.org/10.3389/fnins.2018.00774

Deep Learning With Spiking Neurons: Opportunities and Challenges

🚺 Michael Pfeiffer* and 🎆 Thomas Pfeil

Bosch Center for Artificial Intelligence, Robert Bosch GmbH, Renningen, Germany

Spiking neural networks (SNNs) are inspired by information processing in biology, where sparse and asynchronous binary signals are communicated and processed in a massively parallel fashion. SNNs on neuromorphic hardware exhibit favorable properties such as low power consumption, fast inference, and event-driven information processing. This makes them interesting candidates for the efficient implementation of deep neural networks, the method of choice for many machine learning tasks. In this review, we address the opportunities that deep spiking networks offer and investigate in detail the challenges associated with training SNNs in a way that makes them competitive with conventional deep learning, but simultaneously allows for efficient mapping to hardware. A wide range of training

- Opportunities
 - Sparse, asynchronous and binary signals are processed massively in parallel
 - On neuromorphic hardware: Low power, low latency, event-driven
 - Similarities between spiking neural networks and binary neural networks
- ► Challenges
 - Approaches for training
 - Conversion (of constrained networks)
 - Spiking variants of error backpropagation
 - Local learning rules like spike-timing dependent plasticity
 - High computational cost for training
 - Local on-chip learning
 - Datasets
 - Exploitation of temporal codes

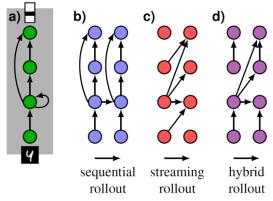
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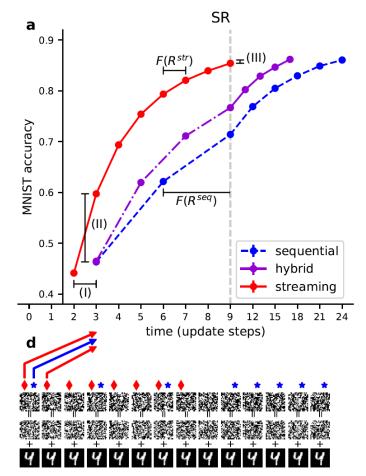


Neuromorphic and AI research at BCAI The streaming rollout of deep networks - towardsfully model-parallel execution

Different rollouts for the same network



- Advantages of streaming rollouts
 - ► Fully model-parallel execution
 - Shorter response time (I)
 - Highest sampling and output frequency
 - Temporal integration via skip connections
 - Usually better early (II) and comparable late (III) performance





SNNs for Efficient Sequence Processing Efficient Processing of Spatio-Temporal Data Streams With Spiking NNs

Goal

- Efficient classification on event streams
- Foundation
 - Streaming rollouts¹
 - Execute an ANN with skip connections in an efficient way
 - > ANN-SNN conversion²
 - Convert trained ANNs to SNNs for efficient classification of static data (images)

Result

> Convert ANNs with skip connections to SNNs for efficient classification of sequential data (frames)

¹ Fischer, Köhler and Pfeil, *The streaming rollout of deep networks – towards fully model-parallel execution*, NeurIPS 2018

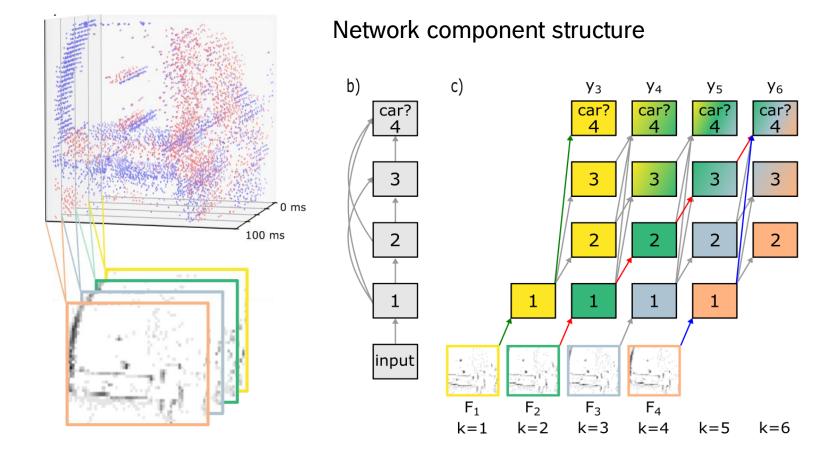
² Rueckauer, B., Lungu, I.-A., Hu, Y., Pfeiffer, M., and Liu, S.-C, *Conversion of continuous-valued deep networks to efficient eventdriven networks for image classification*, Frontiers in Neuroscience 2017

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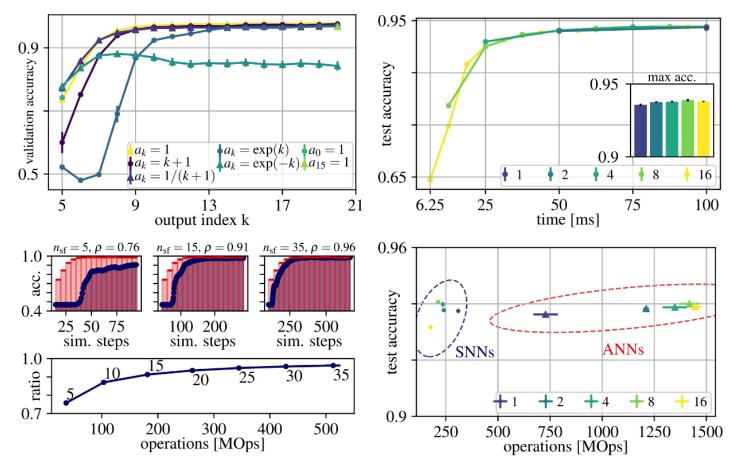


SNNs for Efficient Sequence Processing Approach: Transport information via delay





SNNs for Efficient Sequence Processing ANN-SNN Conversion for sequential data





SNNs for Efficient Sequence Processing Results

- > We always provide the most accurate model
- > All our models have fewer parameters than other approaches
- > SNNs always need fewer operations to reach approximately the same accuracy

N-CARS	acc.	# params	# ops [MOps]	DvsGesture	acc.	# param	s $\# \text{ ops } [MOps]$
HATS/linear SVM (Sironi et al., 2018)	90.2	_	-	10 classes			
Rec. U-Net+CNN (Rebecq et al., 2019)	91.0	$> 10^{6}$	_	SNN on TrueNorth (Amir et al., 2017)	96.7	$1.5\cdot 10^6$	-
ResNet-34 (Gehrig et al., 2019)	92.5	10^{7}		SNN with backprop (Shrestha and Orchard,	2018) $93.64(\pm 0$.49) -	-
e		10^{10}	-	PointNet-like ANN (Wang et al., 2019)	97.08	-	-
Streaming rollout ANN (ours)	$94.00(\pm 0.05)$	2	$1420(\pm 47)$	Streaming rollout ANN (ours)	$97.16(\pm 0$	$(0.11) 5 \cdot 10^5$	$8150(\pm 740)$
Converted SNN (ours)	$94.07(\pm 0.05)$	10^{5}	$212.9(\pm 2.5)$	Converted SNN (ours)	$96.97(\pm 0$.17) $5 \cdot 10^5$	$651(\pm 43)$
				11 classes			
				SNN on TrueNorth (Amir et al., 2017)	94.59	$1.5\cdot 10^6$	-
N-MNIST	acc.	# params	# ops [MOps]	PointNet-like ANN (Wang et al., 2019)	95.32	-	-
SNN with backprop (Lee et al., 2016)	98.66	$2 \cdot 10^{6}$	_	Streaming rollout ANN (ours)	$95.68(\pm0.01)$	$(0.32) 8 \cdot 10^5$	$15000(\pm 1000)$
SNN with backprop (Wu et al., 2019)	99.53	$2 \cdot 10^{6}$		Converted SNN (ours)	$95.56(\pm 0$.14) $8 \cdot 10^5$	$931(\pm 24)$
HATS/linear SVM (Sironi et al., 2019)	99.1	2.10	-				
		-	-	CIFAR10-DVS	acc.	# params	# ops [MOps]
Rec. U-Net+CNN (Rebecq et al., 2019)	98.3	$> 10^{6}$	-		F.2. (// 1	
Streaming rollout ANN (ours)	$99.56(\pm 0.01)$	$3 \cdot 10^5$	$3500(\pm 360)$	HATS/linear SVM (Sironi et al., 2018)	52.4		
Converted SNN (ours)	$99.54(\pm 0.01)$	$3 \cdot 10^5$	$460(\pm 38)$	SNN with backprop (Wu et al., 2019)	60.5	$2 \cdot 10^{6}$	
				Streaming rollout ANN (ours)	$66.75(\pm 0.22)$	$5 \cdot 10^5$	$8800(\pm 1300)$

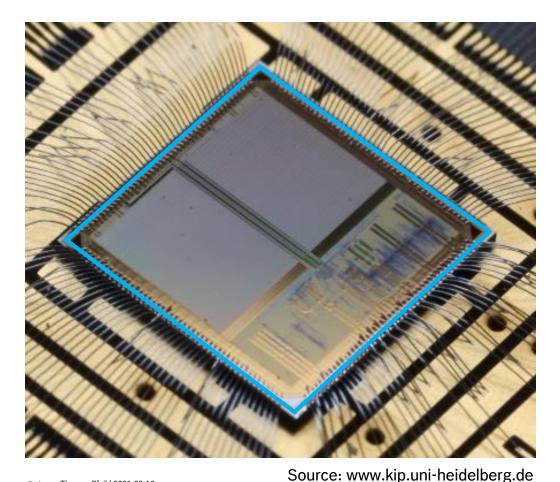
Converted SNN (ours)

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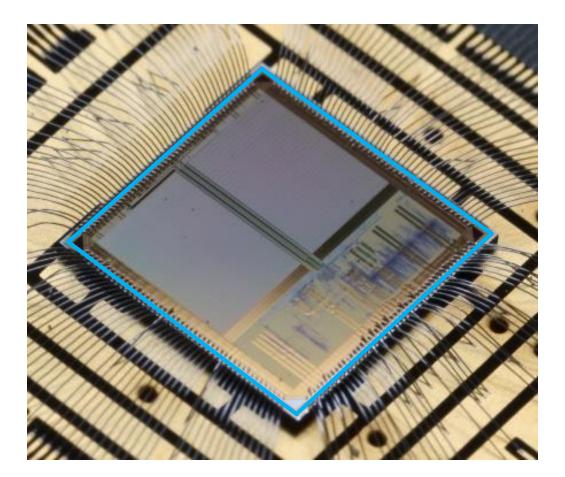
 $1551(\pm 65)$

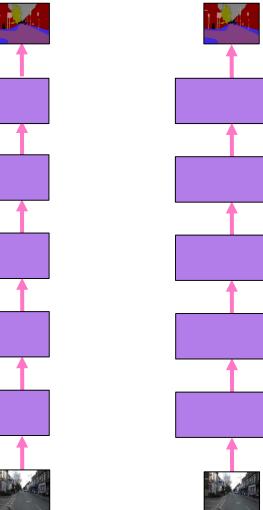
 $65.61(\pm 0.20)$ $5 \cdot 10^5$



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- Novel hardware accelerators for deep neural networks Massively parallel In-memory computation Advantages – High throughput - Low latency - Low power Disadvantages – Area BOSCH

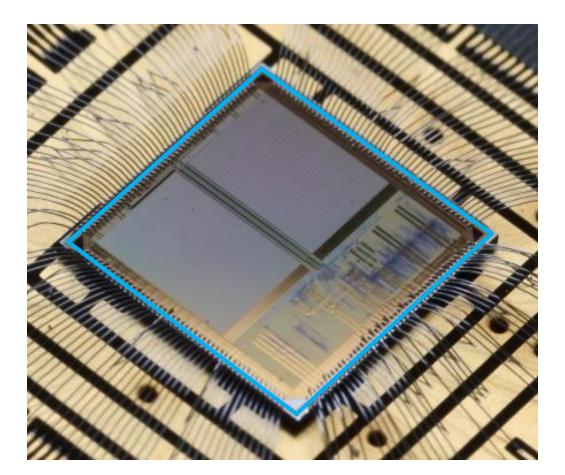




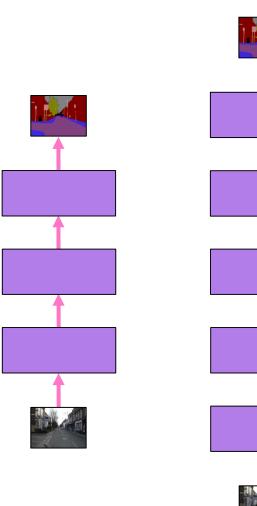
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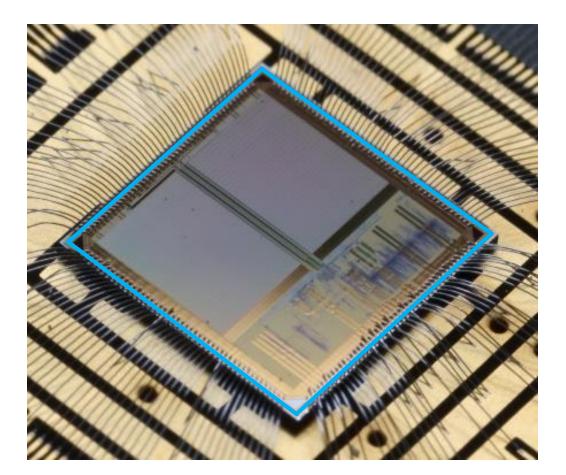


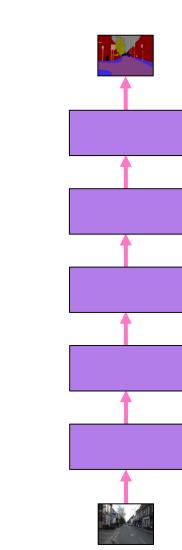
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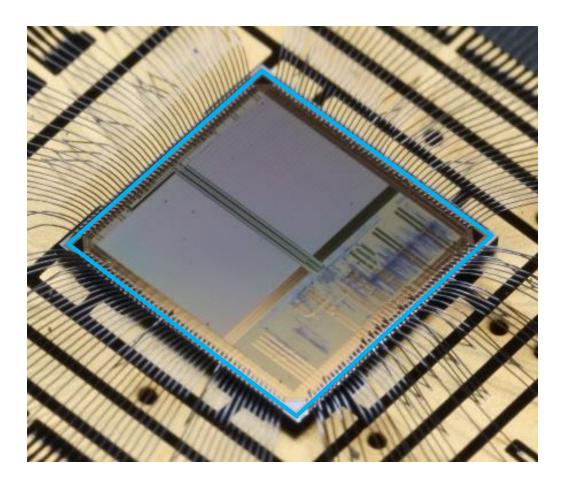
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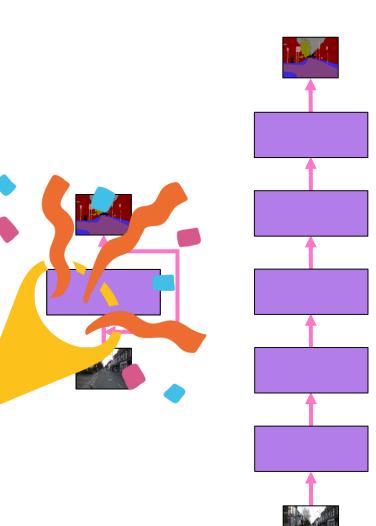
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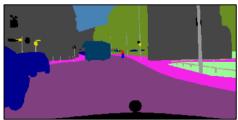


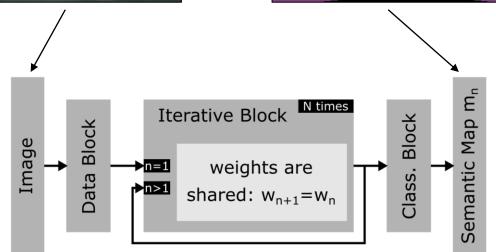
ItNet: Iterative Neural Networks Task and network model

Task

- Semantic segmentation
 - Cityscapes dataset (2 mega pixels)
 - CamVid dataset
- ► Target
 - Tiny graph
 - Few billion multiply accumulate operations
- Network model
 - Data block
 - Down-sampling (4-fold) and preparation for iterative block
 - Iterative block
 - Weight are shared between iteration
 - Classification block
 - Classification and up-sampling







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ItNet: Iterative Neural Networks Network training with intermediate outputs

Training with backpropagation using the loss function

$$\mathcal{L} = \sum_{n} \bar{a}_n c_n(\tilde{m}_n, m_n)$$

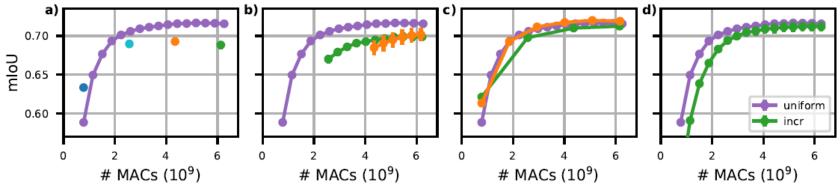
with \bar{a}_n the weight of the output n

- Application
 - Anytime prediction
 - Efficiently use limited computational budget

- Results
 - Early outputs improve accuracy of late outputs (a-d)
 - Thinned out outputs result in less constraints and, hence, higher accuracy (c)

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 Uniform weights are better than linearly increasing weights (d)

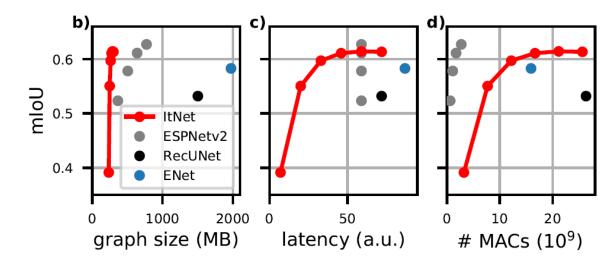


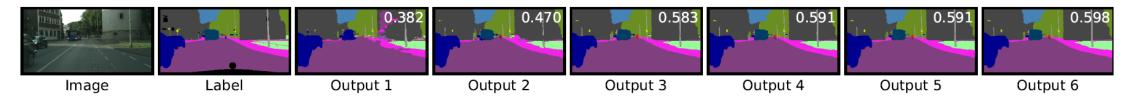
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ItNet: Iterative Neural Networks Results for the Cityscapes dataset

- Compared to the state-of-the-art in terms of MACs (ESPNetv2), ItNets
 - shrink the graph by a factor of 2 (b)
 - allow for anytime prediction with low latencies
 (c)
 - ▶ require 10 times more MACs (d)
- Training can be scaled by, e.g., "Multiscale Deep Equilibrium Models" (Bai, Koltun, Kolter at NeurIPS 2020)



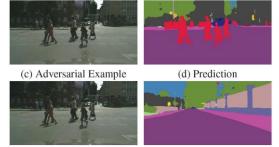




Neuromorphic and AI research at BCAI Highlights of deep learning research at BCAI

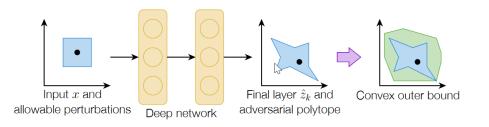
Metzen, J. H., Mummadi, C. K., M., Brox, T., & Fischer, V. Universal adversarial perturbations against semantic image segmentation. (a) Image (b) Prediction

ICCV 2017

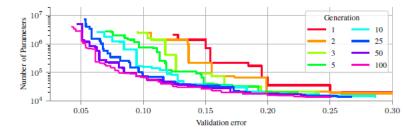


► Wong, E., & Kolter, Z.

Provable Defenses against Adversarial Examples via the Convex Outer Adversarial Polytope. ICML 2018



 Elsken, T., Metzen, J. H., & Hutter, F.
 Efficient Multi-Objective Neural Architecture Search via Lamarckian Evolution.
 ICLR 2018



 Schönfeld, E., Schiele, B., & Khoreva, A.
 A U-Net Based Discriminator for Generative Adversarial Networks CVPR 2020



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THANK YOU!



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