Efficient GPU training of SNNs

James Knight & Thomas Nowotny









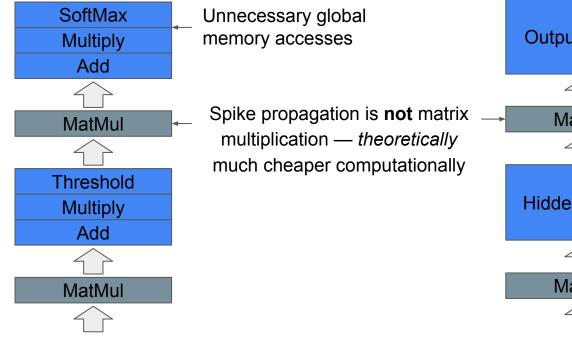
Spiking Neural Network acceleration

- Comp Neuro
 - Long history of simulators for efficiently processing sparse connectivity and activity
 - Focus on simulating single instances of (potentially very) large models
 - Historically, distributed CPU was platform of choice
- Neuromorphic hardware
 - Potential 1000-1000000x energy saving compared to standard hardware [1]
 - On-chip learning still challenging
 - Real-time isn't fast enough for training with current data-hungry algorithms?
- ML using SNNs
 - PyTorch/TensorFlow/JAX used for GPU acceleration by treating SNN as RNNs
 - Auto diff + surrogate gradients/spike times used to train SNNs using BPTT

Frenkel, C., Bol, D., & Indiveri, G. (2021). Bottom-Up and Top-Down Neural Processing Systems Design: Neuromorphic Intelligence as the Convergence of Natural and Artificial Intelligence. 1–25. Retrieved from http://arxiv.org/abs/2106.01288

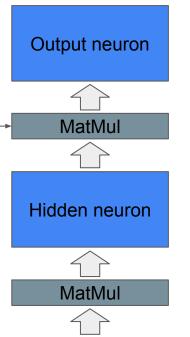
SNNs as computational graphs

Naive



= 8 kernel launches ≈ 40µs latency

With JIT/custom kernels



= 4 kernel launches ≈ 20µs latency

GeNN

- C++ library for generating SNN simulation code
- Backends to generate CUDA, OpenCL and C++ code
- All features available from Python
- Past focus on Computational Neuroscience and Neurorobotics
- Maximal user control

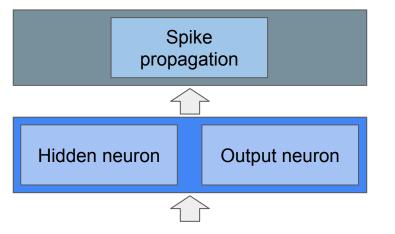
https://genn-team.github.io/genn/

Knight, J. C., & Nowotny, T. (2018). GPUs Outperform Current HPC and Neuromorphic Solutions in Terms of Speed and Energy When Simulating a Highly-Connected Cortical Model. Frontiers in Neuroscience, 12(December), 1–19. <u>https://doi.org/10.3389/fnins.2018.00941</u>

Knight, J. C., & Nowotny, T. (2021). Larger GPU-accelerated brain simulations with procedural connectivity. Nature Computational Science, 1(2), 136–142. https://doi.org/10.1038/s43588-020-00022-7

Knight, J. C., Komissarov, A., & Nowotny, T. (2021). PyGeNN: A Python Library for GPU-Enhanced Neural Networks. Frontiers in Neuroinformatics, 15(April). https://doi.org/10.3389/fninf.2021.659005

SNNs in GeNN

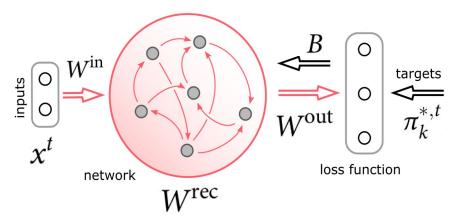


= 2 kernel launches \approx 10µs latency "pipelined"

Spike transmission isn't instantaneous

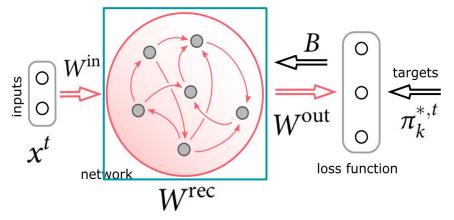
- Breaks dependencies model doesn't need to be a directed acyclical graph
- All neuron and synapse updates can be *fused* [1]

1. Knight, J. C., & Nowotny, T. (2021). Larger GPU-accelerated brain simulations with procedural connectivity. Nature Computational Science, 1(2), 136–142. https://doi.org/10.1038/s43588-020-00022-7

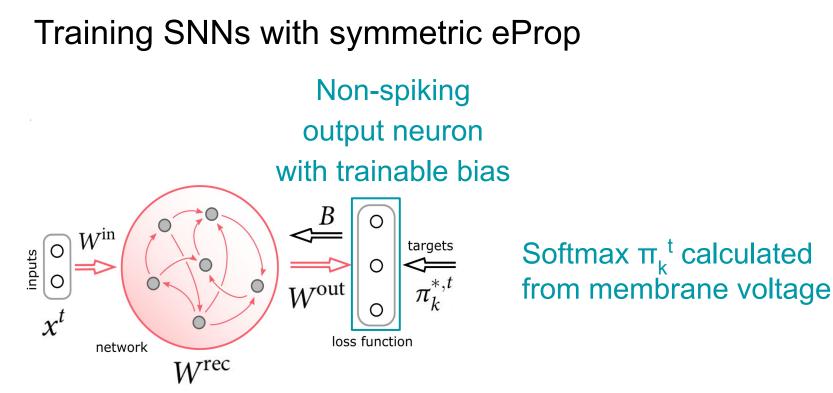


Zenke, F., & Neftci, E. O. (2021). Brain-Inspired Learning on Neuromorphic Substrates. Proceedings of the IEEE, 1–16. https://doi.org/10.1109/JPROC.2020.3045625

LIF neuron with adaptation and relative reset



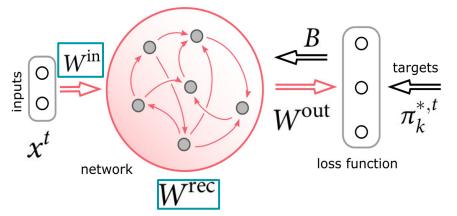
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Per-synapse eligibility traces and supervised learning rule

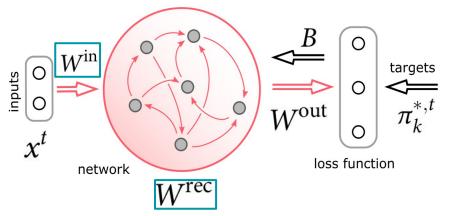
$$\Delta W_{ji}^{\text{rec}} = -\eta \sum_{t} \underbrace{\left(\sum_{k} B_{jk}(\pi_{k}^{t} - \pi_{k}^{*,t})\right)}_{=L_{i}^{t}} \overline{e}_{ji,a}^{t} \qquad \Delta W_{ji}^{\text{rec}} = -\eta \sum_{t} \underbrace{\left(\sum_{k} B_{jk}(\pi_{k}^{t} - \pi_{k}^{*,t})\right)}_{=L_{i}^{t}} \overline{e}_{ji}^{t}.$$



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Per-synapse eligibility traces and supervised learning rule

 $e_{ji,a}^{t+1} = \underline{\psi_j^t} \bar{z}_i^{t-1} + (\rho - \underline{\psi_j^t} \beta) e_{ji,a}^t \quad e_{ji}^t = \underline{\psi_j^t} \left(\bar{z}_i^{t-1} - \beta e_{ji,a}^t \right)$



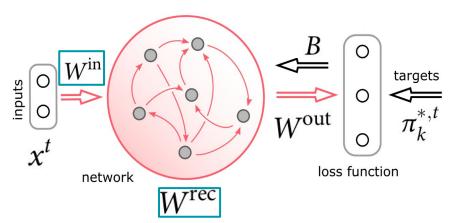
Postsynaptic neuron surrogate gradient

 $\Delta W_{ji}^{\text{rec}} = -\eta \sum_{t} \underbrace{\left(\sum_{k} B_{jk}(\pi_{k}^{t} - \pi_{k}^{*,t})\right)}_{=L_{i}^{t}} \bar{e}_{ji}^{t}.$

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Per-synapse eligibility traces and supervised learning rule

 $e_{ji,a}^{t+1} = \psi_j^t \overline{z}_i^{t-1} + (\rho - \psi_j^t \beta) e_{ji,a}^t \quad e_{ji}^t = \psi_j^t \left(\overline{z}_i^{t-1} - \beta e_{ji,a}^t \right)$





Filtered presynaptic activity

Zenke, F., & Neftci, E. O. (2021). Brain-Inspired Learning on Neuromorphic Substrates. Proceedings of the IEEE, 1–16. https://doi.org/10.1109/JPROC.2020.3045625

Extensions to GeNN

Batching

- Instantiated multiple copies of model simultaneously
- Variables e.g. weights can be shared between instances

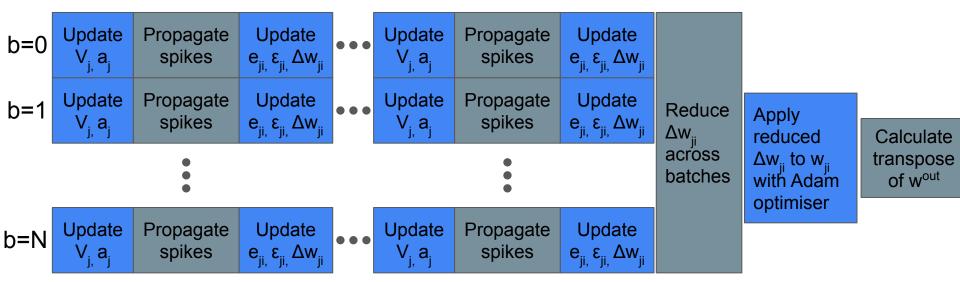
Custom updates

- Arbitrary user-defined operations optimizer
- Efficient matrix transpose weight transport
- Efficient batch reduction operations (NCCL) parallel training

Implementing eProp

t=0

t=K-1



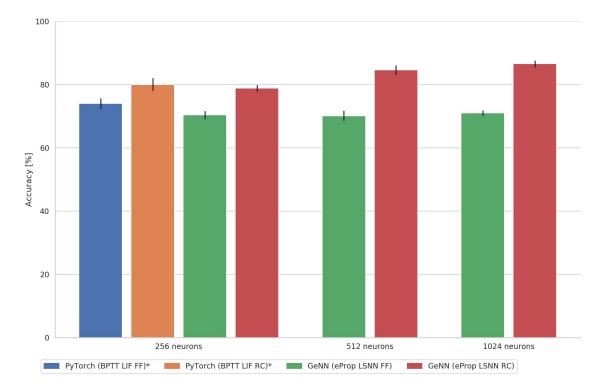
Spiking Heidelberg Digits



- 10420 recordings
- 12 speakers
- Digits 0-9 in English and German
- Converted to 700 spike trains using inner ear model

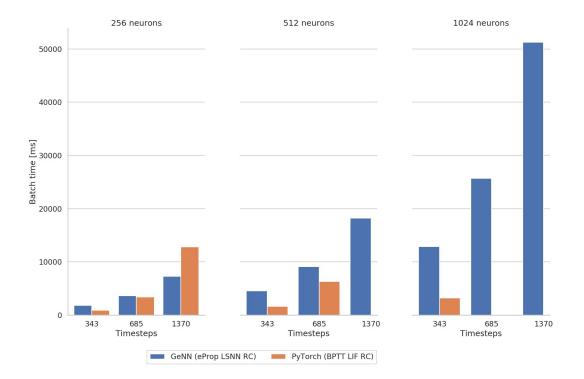
Cramer, B., Stradmann, Y., Schemmel, J., & Zenke, F. (2020). The Heidelberg Spiking Data Sets for the Systematic Evaluation of Spiking Neural Networks. IEEE Transactions on Neural Networks and Learning Systems. https://doi.org/10.1109/TNNLS.2020.3044364

Classification accuracy: Spiking Heidelberg Digits



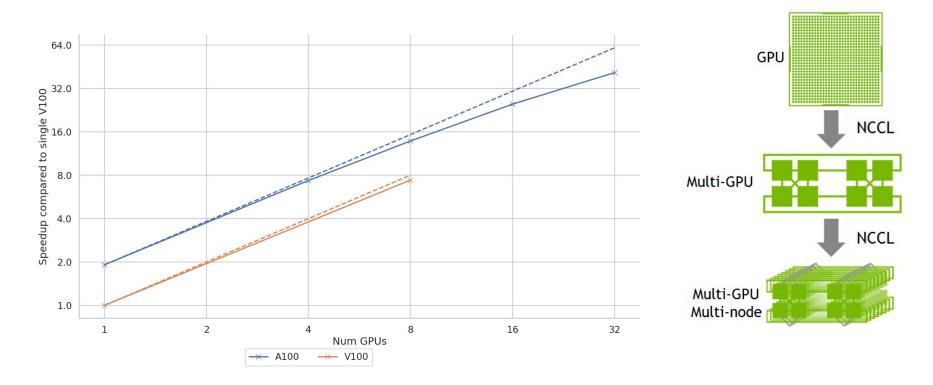
* Zenke, F., & Vogels, T. P. (2020). The remarkable robustness of surrogate gradient learning for instilling complex function in spiking neural networks. *BioRxiv*, 1–22. https://doi.org/10.1101/2020.06.29.176925

Training performance: Spiking Heidelberg Digits

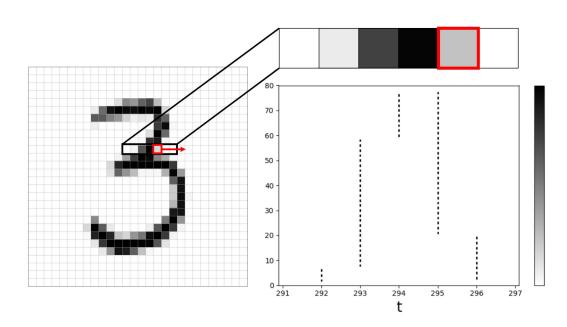


https://github.com/fzenke/spytorch

Multi-GPU training: Spiking Heidelberg Digits

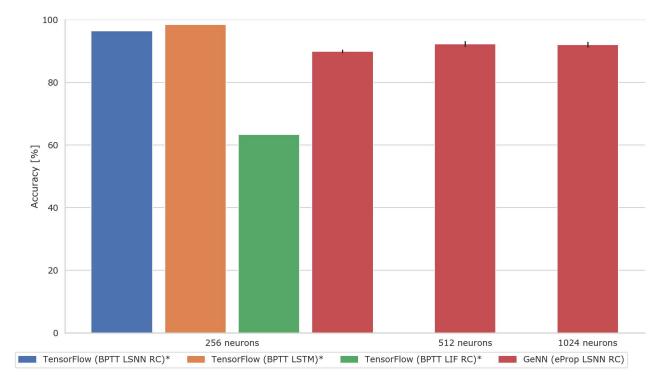


Spiking Sequential MNIST



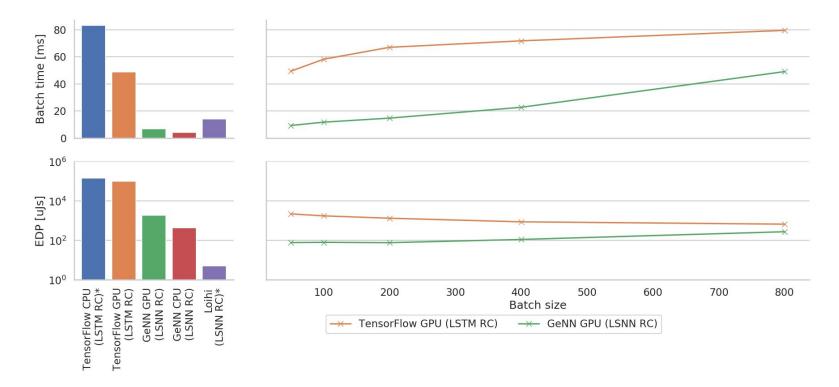
- Pixel values of MNIST digits presented in fixed order
 - Each neuron represents a threshold crossing of a gray value

Classification accuracy: Spiking Sequential MNIST



* Plank, P., Rao, A., Wild, A., & Maass, W. (2021). A Long Short-Term Memory for Al Applications in Spike-based Neuromorphic Hardware. Retrieved from http://arxiv.org/abs/2107.03992

Inference performance: Spiking Sequential MNIST



* Plank, P., Rao, A., Wild, A., & Maass, W. (2021). A Long Short-Term Memory for Al Applications in Spike-based Neuromorphic Hardware. Retrieved from http://arxiv.org/abs/2107.03992



EventProp: Fully event-driven learning

Free dynamics	Transition condition	Jumps at transition	
$\tau_{\rm mem} \frac{\rm d}{{\rm d}t} V = -V + I$ $\tau_{\rm syn} \frac{\rm d}{{\rm d}t} I = -I$	$(V)_n - \vartheta = 0$ $(\dot{V})_n \neq 0$ for any <i>n</i>	$(V^+)_n = 0$ $I^+ = I^- + We_n$	

$$\mathcal{L} = l_{\mathrm{p}}(t^{\mathrm{post}}) + \int_{0}^{T} l_{V}(V(t), t) \mathrm{d}t.$$

https://youtu.be/oM7XEsDVcNg

Wunderlich, T. C., & Pehle, C. (2021). Event-based backpropagation can compute exact gradients for spiking neural networks. Scientific Reports, 11(1), 12829. https://doi.org/10.1038/s41598-021-91786-z



EventProp: Fully event-driven learning

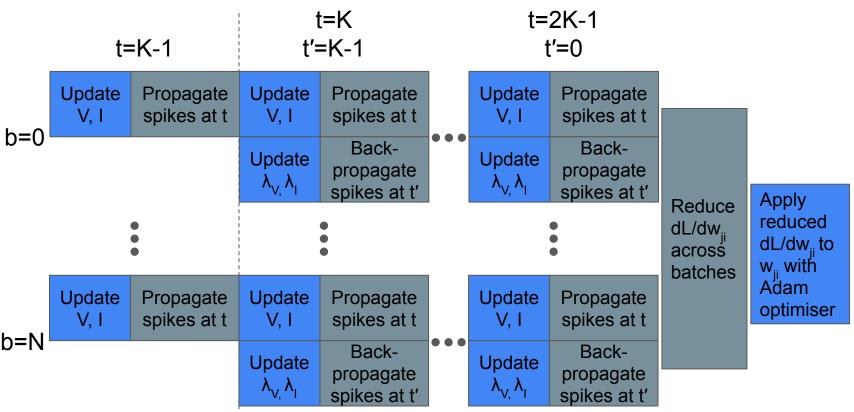
Free dynamics	Transition condition	Jump at transition
$ au_{ m mem} \lambda'_V = -\lambda_V - rac{\partial l_V}{\partial V} \ au_{ m syn} \lambda'_I = -\lambda_I + \lambda_V$	$t - t_k^{\text{post}} = 0$ for any k	$\begin{aligned} (\lambda_V^-)_{n(k)} &= (\lambda_V^+)_{n(k)} + \frac{1}{\tau_{\text{mem}}(\dot{V}^-)_{n(k)}} \left[\vartheta (\lambda_V^+)_{n(k)} \right. \\ &+ \left(W^\top (\lambda_V^+ - \lambda_I) \right)_{n(k)} + \frac{\partial l_p}{\partial t_k^{\text{post}}} + l_V^ l_V^+ \right] \end{aligned}$

$$\frac{\mathrm{d}\mathcal{L}}{\mathrm{d}w_{ji}} = -\tau_{\mathrm{syn}} \sum_{\mathrm{spikes from } i} (\lambda_I)_j,$$

Wunderlich, T. C., & Pehle, C. (2021). Event-based backpropagation can compute exact gradients for spiking neural networks. Scientific Reports, 11(1), 12829. https://doi.org/10.1038/s41598-021-91786-z

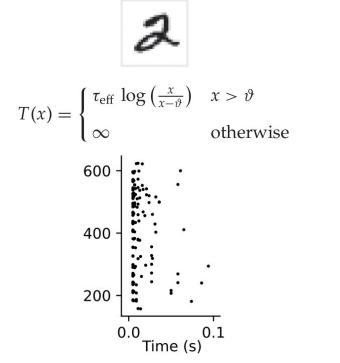


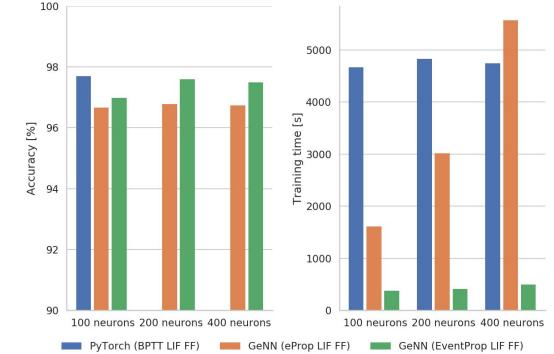
Implementing EventProp





Fully event-driven learning: Latency-encoded MNIST





* Zenke, F., & Vogels, T. P. (2020). The remarkable robustness of surrogate gradient learning for instilling complex function in spiking neural networks. *BioRxiv*, 1–22. https://doi.org/10.1101/2020.06.29.176925

Future direction

- Simplifications to eProp [1]
- Applying eProp and EventProp to CNNs
- Deep-R [2]
- New higher-level frontend library [3]
- FPGA backend

- Frenkel, C., & Indiveri, G. (2022). ReckOn: A 28nm Sub-mm2 Task-Agnostic Spiking Recurrent Neural Network Processor Enabling On-Chip Learning over Second-Long Timescales. 2022 IEEE International Solid- State Circuits Conference (ISSCC), 1–3. <u>https://doi.org/10.1109/ISSCC42614.2022.9731734</u>
- 2. Bellec, G., Kappel, D., Maass, W., & Legenstein, R. (2018). Deep rewiring: Training very sparse deep networks. 6th International Conference on Learning Representations, ICLR 2018 Conference Track Proceedings, 1–24.
- 3. Turner, J. P., Knight, J. C., Subramanian, A., & Nowotny, T. (2022). mlGeNN: accelerating SNN inference using GPU-enabled neural networks. Neuromorphic Computing and Engineering, 2(2), 024002. <u>https://doi.org/10.1088/2634-4386/ac5ac5</u>

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Any questions

J.C.Knight@sussex.ac.uk

